Robot Detection for Usage Statistics

Short Presentation to introduce the breakout session "Robots"

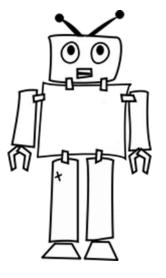
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Workshop "Usage Statistics and Beyond" | Open Access Statistics - From a Project to a Service | 22-23 April 2013 | Matthias Hitzler

Overview

- 1. Robot definition
- 2. Identifying robots
- 3. Filtering robots in Open Access Statistics
- 4. A common list of robots
- 5. Suggestions for discussion





Robot Definition



"A robot is a program that automatically traverses the web's hypertext structure by retrieving a document, and recursively retrieving all documents that are referenced." (Martijn Koster 1999)

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Robot Definition



 good intentions

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"Ethical" robots

- reveal themselves
- use robots.txt

- bad intentions
- do not reveal themselves
- ignore robots.txt

"Malicious" robots

Identifying Robots



Different approaches:

- IP adress
- User agent
- Heuristic methods
 - Time patterns
 - Document-related hits
 - Referer
 - Hit on robot.txt
 - Hit method

"Mosilla/4.0 (compatible; MSIE 8.0; Windows NT 5.1; Trident/4.0; GTB7.3; Mosilla/4.0 (compatible; MSIE 6.0; Windows NT 5.1; SV1) ; .NET CLR 1.1.4322; osilla/4.0 (compatible; MSIE 8.0; Windows NT 5.1; Trident/4.0; GTB7.3; Mosilla/4.0 (compatible; MSIE 6.0; Windows NT 5.1; SV1) ; .NET CLR 1.1.4322; 00" "Mosilla/4.0 (compatible; MSIE 8.0; Windows NT 5.1; Trident/4.0; GTB7.3; Mosilla/4.0 (compatible; MSIE 6.0; Windows NT 5.1; SV1) ; .NET CLR 1.1.4322; "Mosilla/4.0 (compatible; MSIE 8.0; Windows NT 5.1; Trident/4.0; GTB7.3; Mosilla/4.0 (compatible; MSIE 6.0; Windows NT 5.1; SV1) ; .NET CLR 1.1.43 ""Mosilla/4.0 (compatible; MSIE 8.0; Windows NT 5.1; Trident/4.0; GTB7.3; Mosilla/4.0 (compatible; MSIE 6.0; Windows NT 5.1; SV1) ; .NET CLR 1.1.43 0" "Mosilla/4.0 (compatible; MSIE 8.0; Windows NT 5.1; Trident/4.0; GTB7.3; Mosilla/4.0 (compatible; MSIE 6.0; Windows NT 5.1; SV1) ; .NET CLR 1.1.43 0" "Mosilla/4.0 (compatible; MSIE 8.0; Windows NT 5.1; Trident/4.0; GTB7.3; Mosilla/4.0 (compatible; MSIE 6.0; Windows NT 5.1; SV1) ; .NET CLR 1.1.43 0" "Mosilla/4.0 (compatible; MSIE 8.0; Windows NT 5.1; Trident/4.0; GTB7.3; Mosilla/4.0 (compatible; MSIE 6.0; Windows NT 5.1; SV1) ; .NET CLR 1.1.43 0" "Mosilla/4.0 (compatible; MSIE 8.0; Windows NT 5.1; Trident/4.0; GTB7.3; Mosilla/4.0 (compatible; MSIE 6.0; Windows NT 5.1; SV1) ; .NET CLR 1.1.43 0" "Mosilla/4.0 (compatible; MSIE 8.0; Windows NT 5.1; Trident/4.0; GTB7.3; Mosilla/4.0 (compatible; MSIE 6.0; Windows NT 5.1; SV1) ; .NET CLR 1.1.43 00" "Mosilla/4.0 (compatible; MSIE 8.0; Windows NT 5.1; Trident/4.0; GTB7.3; Mosilla/4.0 (compatible; MSIE 6.0; Windows NT 5.1; SV1) ; .NET CLR 1.1.43 00" "Mosilla/4.0 (compatible; MSIE 8.0; Windows NT 5.1; Trident/4.0; GTB7.3; Mosilla/4.0 (compatible; MSIE 6.0; Windows NT 5.1; SV1) ; .NET CLR 1.1.40 00" "Mosilla/4.0 (compatible; MSIE 8.0; Windows NT 5.1; Trident/4.0; GTB7.3; Mosilla/4.0 (compatible; MSIE 6.0; Windows NT 5.1; SV1) ; .NET CLR 1.1.40 00" "Mosilla/4.0 (compatible; MSIE 8.0; Windows NT 5.1; Trident/4.0; GTB7.3; Mosilla/4.0 (compat

Filtering Robots in Open Access Statistics



In Open Access Statistics robots are identified by a list of user agents

Current list contains entries from:

- COUNTER
- PLOS
- NEEO
- AWStats
- robottxt.org

A Common List of Robots



A way to go:

A common, freely available and regulary updated list of robot user agents

```
<robot-list>
<useragent>
  <regEx>Alexandria(\s|\+)prototype(\s|\+)project</regEx>
  <sourceRef id="12" />
  <sourceRef id="11" />
  </useragent>
<useragent>
  <regEx>AllenTrack</regEx>
  <sourceRef id="12" />
  </useragent>
<useragent>
  <regEx>Arachmo</regEx>
  <sourceRef id="12" />
  <sourceRef id="11" />
  </useragent>
<useragent>
  <regEx>Brutus\/AET</regEx>
  <sourceRef id="12" />
  <sourceRef id="11" />
  </useragent>
<useragent>
  <regEx>China\sLocal\sBrowse\s2\.6</regEx>
  <sourceRef id="12" />
  </useragent>
<useragent>
  <regEx>Code\sSample\sWeb\sClient</regEx>
  <sourceRef id="11" />
  </useragent>
<useragent>
  <regEx>ContentSmartz</regEx>
  <sourceRef id="12" />
  </useragent>
```

A Common List of Robots



KE Usage Statistics Guidelines:

- 1. It must be possible to 'timestamp' the list so that agents can refer to specific versions.
- 2. The list must be in a machine-readable format, and preferably in XML.
- 3. The extended list must be approved by COUNTER. Institutions that make use of the extended list should also be able to pass the COUNTER audit.
- 4. It must be possible to indicate the 'source' of each entry in the list (e.g. "COUNTER", "AwStats", "Plos", etc.)
- 5. It must be possible to access the robot list on the basis of a persistent URI.
- 6. It must be possible to manage different versions of the robot list. The most recent version must always be available through a uniform URL.

A Common List of Robots



Following points could be added to this list:

- 1. The list can and should be extended.
- 2. New versions of the list will be published on a regular basis.
- 3. As well as a timestamp, the list should also contain a version number to make it easier to identify and distinguish between different versions.
- 4. The basic list consists of the COUNTER, PLOS and NEEO lists.
- 5. New entries can be submitted by general public.
- 6. New entries are peer reviewed before being added to the list.
- 7. The continued availability of the list must be guaranteed.

Suggestions for Discussion



- Is such a regularly updated robot list desirable?
- How often should the list be updated?
- Who is permitted to add entries to the list?
- Which criteria for detecting and adding to the list must be applied?
- What importance have heuristic methods for detecting robots? How should they be added for usage statistics?